

Bayesian Compressive Sensing Failure Detection in Planar Phased Antenna Arrays

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Abstract

The diagnosis of planar phased antenna arrays is dealt with in this work. The retrieval of the faulty radiators in the antenna under test (*AUT*) is formulated within the compressive sensing (*CS*) framework and it is efficiently and effectively solved through a customized Bayesian *CS* (*BCS*) solver. Robust and reliable reconstructions of the *AUT* status are yielded by means of the proposed diagnosis tool also in presence of significant amounts of noise on processed far-field data. Some numerical experiments are presented to assess the *BCS*-based method when dealing with different operative conditions as well as considering a variation of the array size and failure rate.

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1 Numerical Validation

1.1 Taylor Array, $N = 716$, Isotropic Sources

Parameters

- Gold Array
 - Total number of elements: $N = 716$;
 - Type of elements: isotropic/ideal ¹;
 - Spacing along x and y : $d_x = d_y = 0.5 [\lambda]$;
 - Excitation tapering: Taylor;
 - * Radius: $R = 7.5 [\lambda]$;
 - * Transition index: $t = 3$;
 - * Peak sidelobe level: $PSL = 25$ [dB];

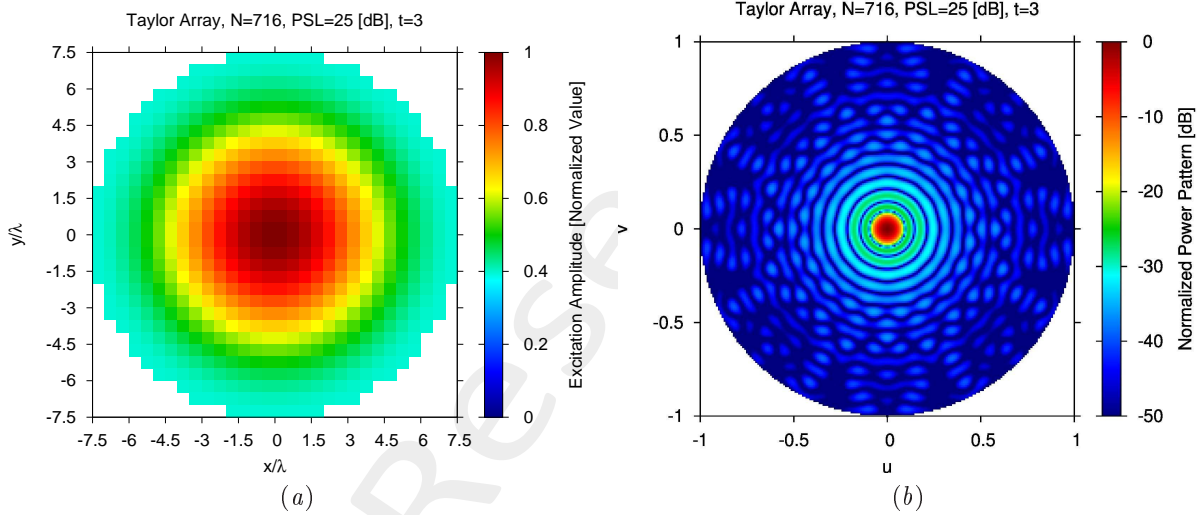


Figure 1: (a) Array excitations and (b) normalized power pattern of the expected array (gold antenna).

- Failed Array
 - Failure factor: $\kappa = 0$ (total failures);
 - Failure rate: see table below;

N_f	$\Phi = \frac{N_f}{N}$
7	1%
14	2%
29	4%
57	8%
115	16%

Table 1: Number of failures (N_f) and corresponding failure rate ($\Phi = \frac{N_f}{N}$).

¹In order to model *isotropic* radiators, let us assume that the embedded elements patterns are equal to $F_\theta^{(n)}(u, v) = 1$ and $F_\varphi^{(n)}(u, v) = 0$, for $n = 1, \dots, N$.

- Measurement set-up
 - Type of sampling: uniform sampling in the (u, v) plane;
 - Number of points in the visible range: $K = 317$;
 - Ratio between measurements and number of elements: $\nu = \frac{K}{N} \simeq 1.0$ ($\nu^{(opt)}$);
- *BCS* solver
 - Noise variance: $\eta = 5 \times 10^{-1}$ ($\eta^{(opt)}$);
 - Tolerance factor: $\iota = 10^{-8}$;
- Signal-to-Noise-Ratio: $SNR = \{10; 20; \dots; 100\}$.

Results

$\Phi = \frac{N_f}{N} = 1\%$ ($N_f = 7$) - Best and Worst *BCS* Reconstructions

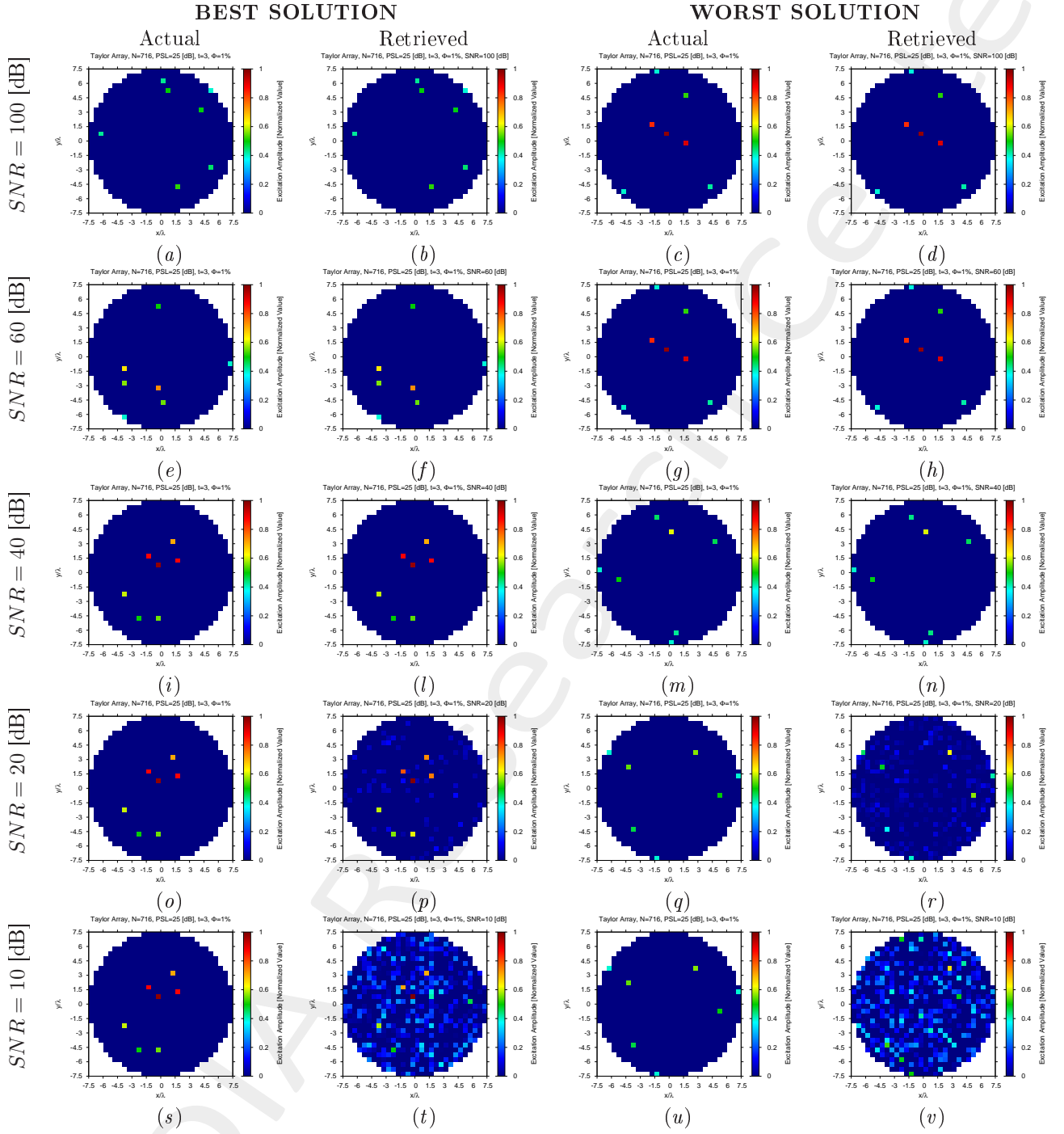


Figure 2: Taylor Array ($N = 716$, $PSL = 25$ [dB], $t = 3$, $\Phi = 1\%$) - Best and worst reconstructions by *BCS* under several *SNR* values.

$\Phi = \frac{N_f}{N} = 2\%$ ($N_f = 14$) - Best and Worst *BCS* Reconstructions

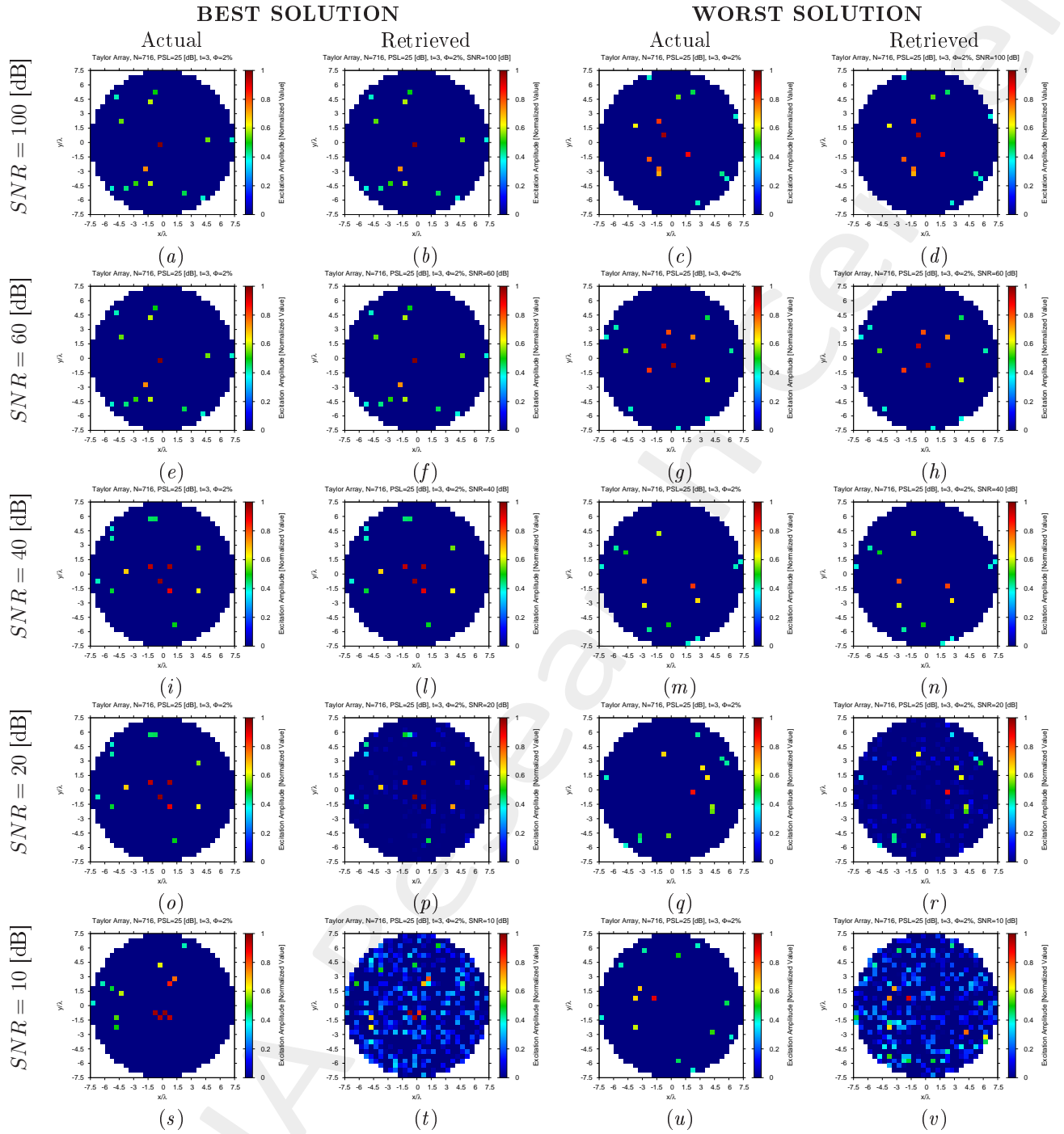


Figure 3: Taylor Array ($N = 716$, $PSL = 25$ [dB], $t = 3$, $\Phi = 2\%$) - Best and worst reconstructions by *BCS* under several *SNR* values.

$\Phi = \frac{N_f}{N} = 4\%$ ($N_f = 29$) - Best and Worst *BCS* Reconstructions

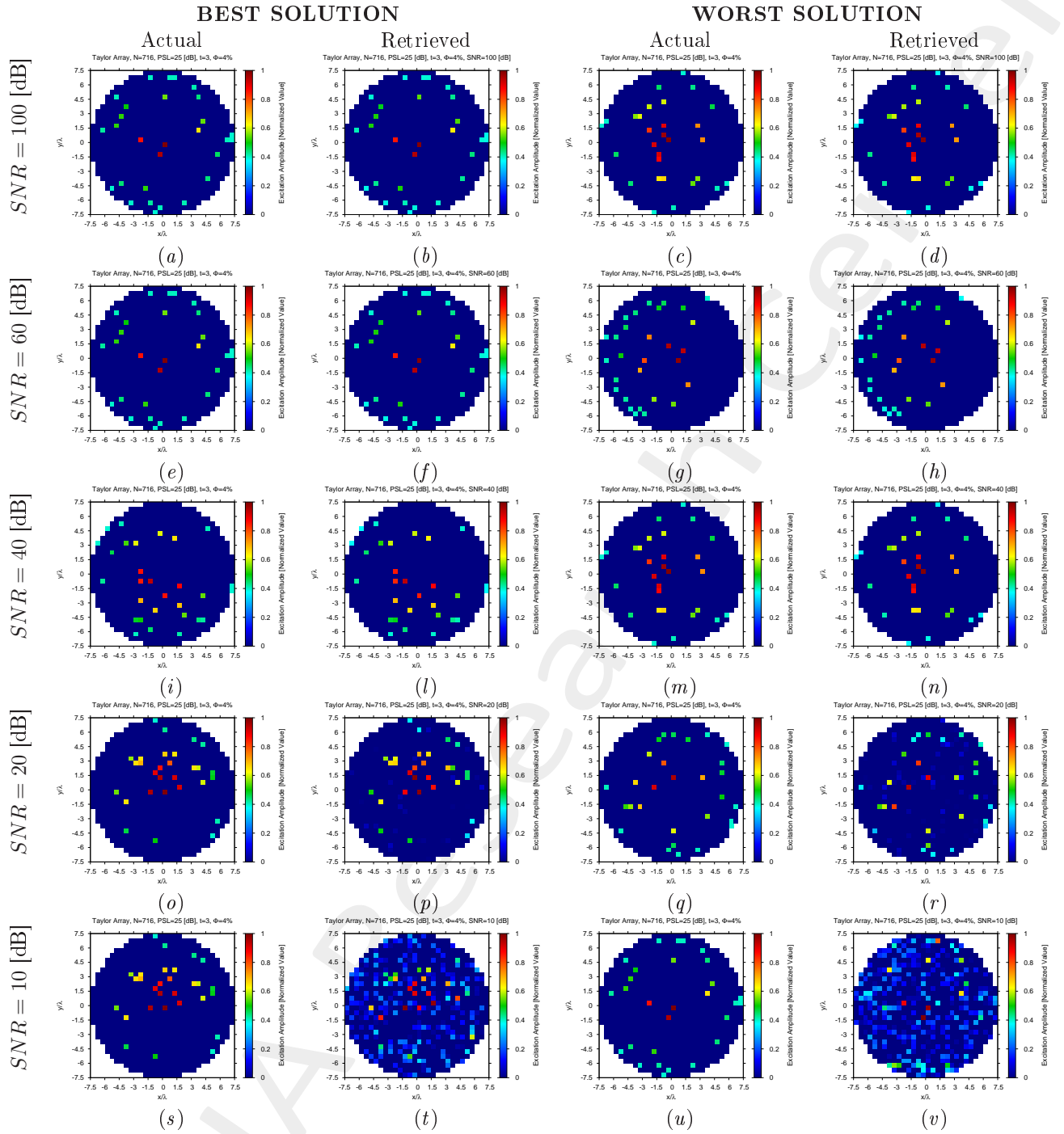


Figure 4: Taylor Array ($N = 716$, $PSL = 25$ [dB], $t = 3$, $\Phi = 4\%$) - Best and worst reconstructions by *BCS* under several *SNR* values.

$\Phi = \frac{N_f}{N} = 8\%$ ($N_f = 57$) - Best and Worst *BCS* Reconstructions

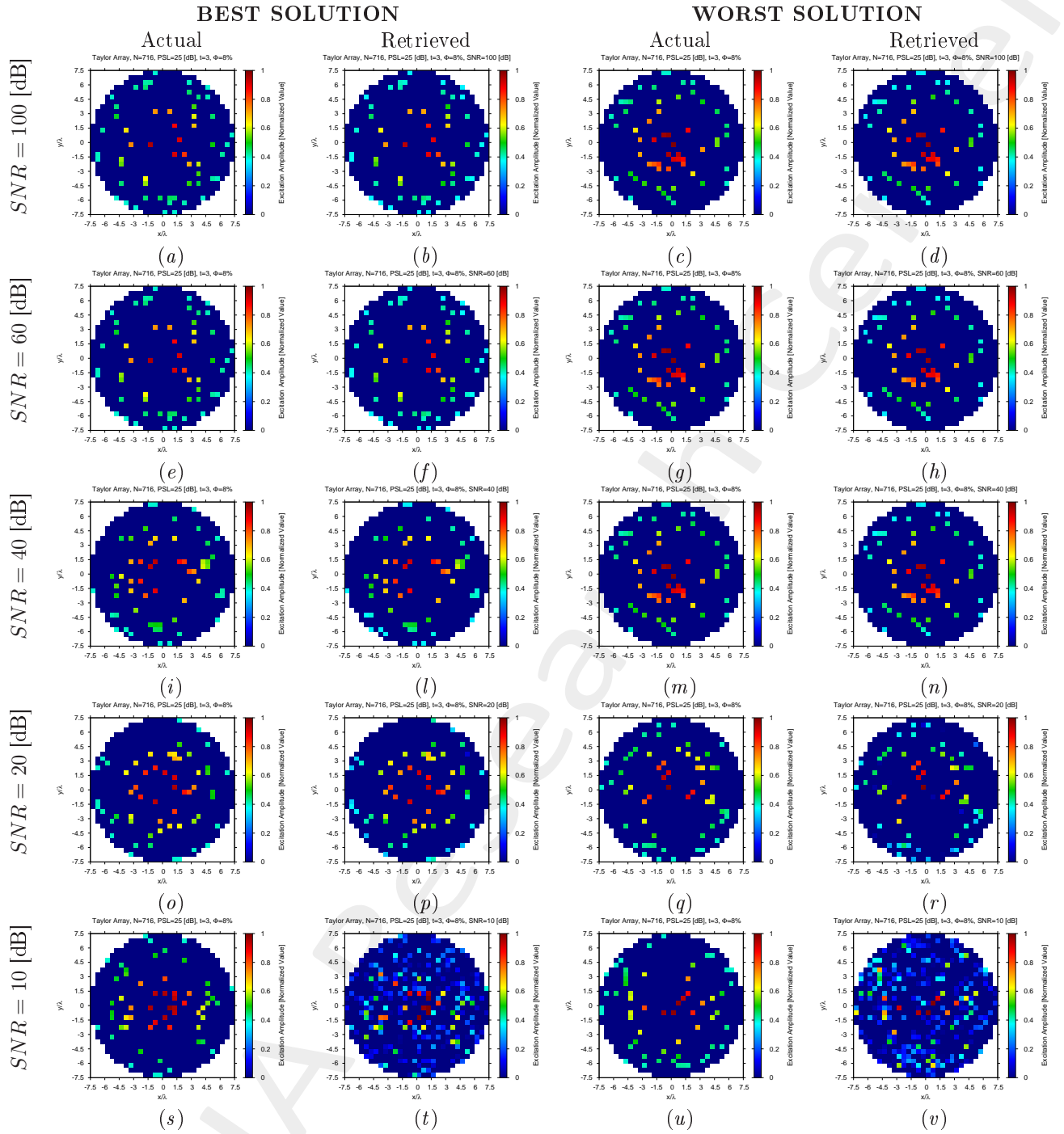


Figure 5: Taylor Array ($N = 716$, $PSL = 25$ [dB], $t = 3$, $\Phi = 8\%$) - Best and worst reconstructions by *BCS* under several SNR values.

Diagnosis Error and Confidence Level

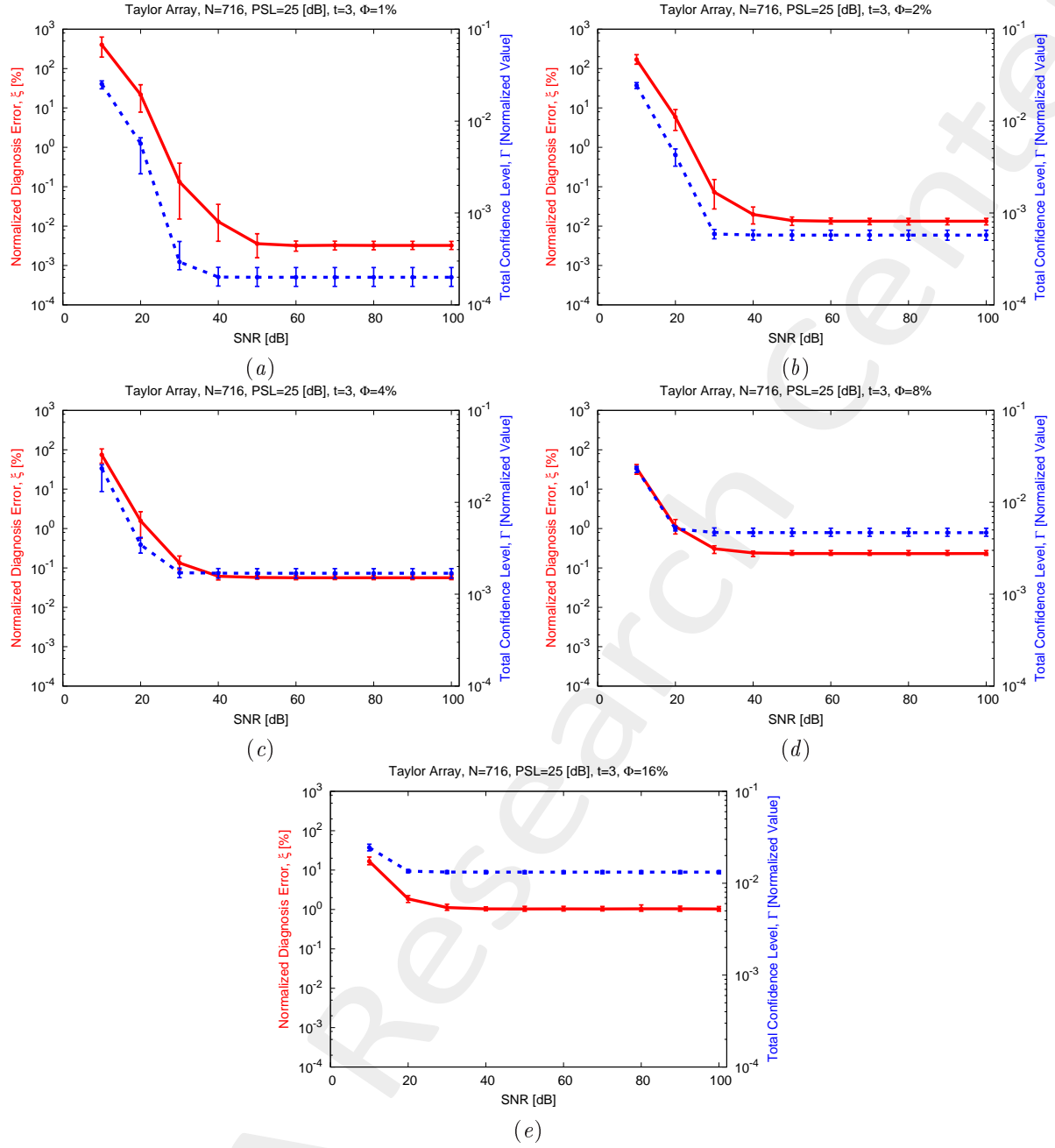


Figure 7: Taylor Array ($N = 716$, $PSL = 25$ [dB], $t = 3$) - Behavior of the average, minimum and maximum diagnosis error (ξ) and total confidence level (Γ) versus the SNR , for (a) $\Phi = 1\%$, (b) $\Phi = 2\%$, (c) $\Phi = 4\%$, (d) $\Phi = 8\%$, and (e) $\Phi = 16\%$.

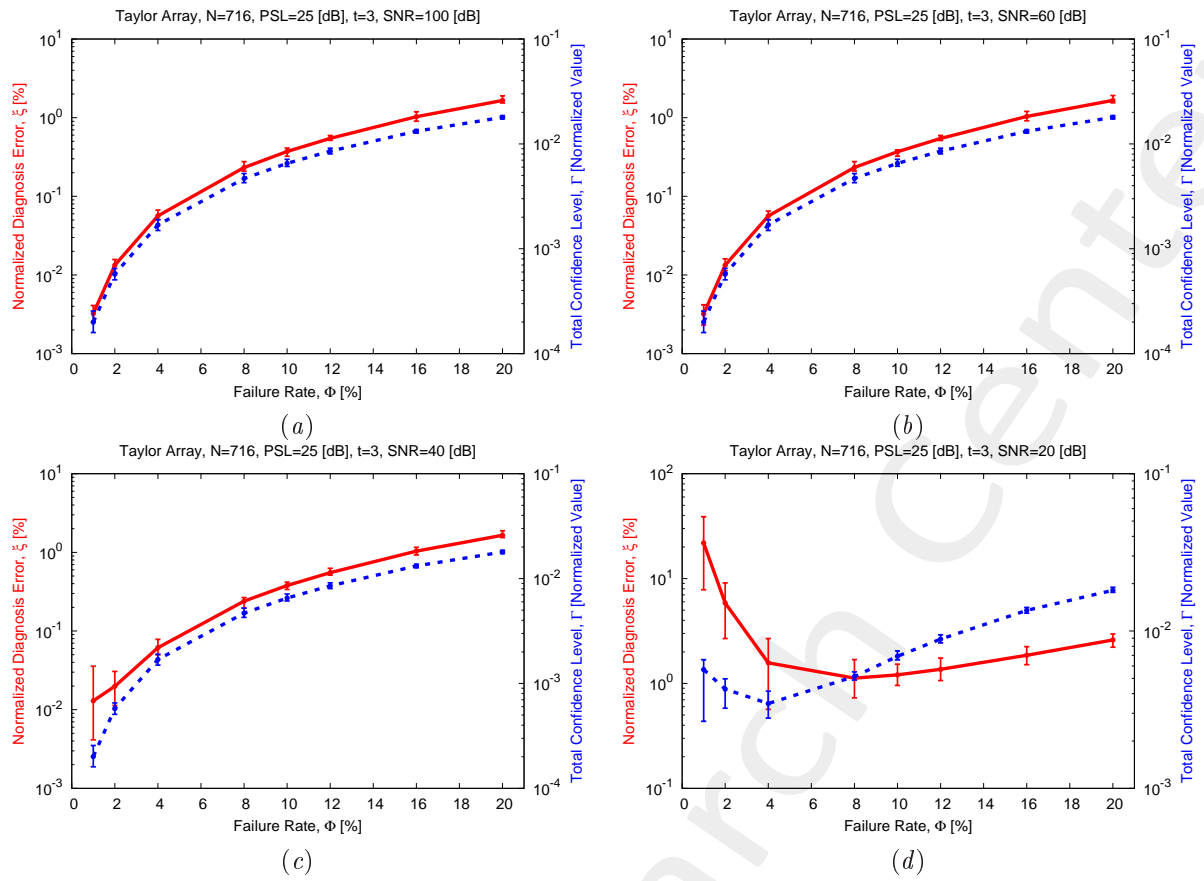


Figure 8: Taylor Array ($N = 716$, $PSL = 25$ [dB], $t = 3$) - Behavior of the average, minimum and maximum diagnosis error (ξ) and total confidence level (Γ) versus the failure rate (Φ), for (a) $SNR = 100$ [dB], (b) $SNR = 60$ [dB], (c) $SNR = 40$ [dB], and (d) $SNR = 20$ [dB].

1.2 Taylor Array, $N = 1264$, Isotropic Sources

Parameters

- Gold Array
 - Total number of elements: $N = 1264$;
 - Type of elements: isotropic/ideal ²;
 - Spacing along x and y : $d_x = d_y = 0.5 [\lambda]$;
 - Excitation tapering: Taylor;
 - * Radius: $R = 9.75 [\lambda]$;
 - * Transition index: $t = 3$;
 - * Peak sidelobe level: $PSL = 25 [\text{dB}]$

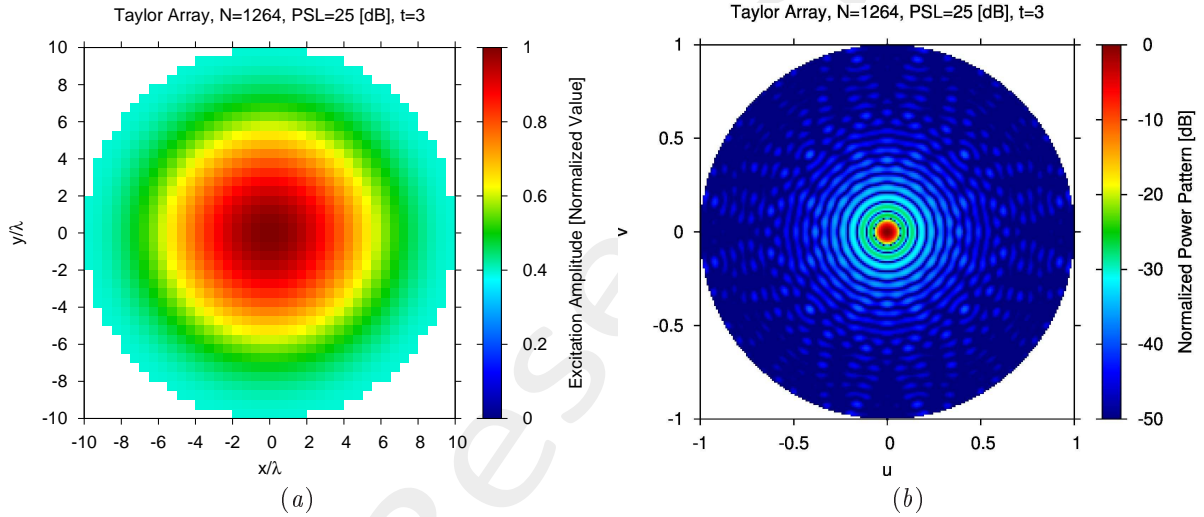


Figure 9: (a) Array excitations and (b) normalized power pattern of the expected array (gold antenna).

- Failed Array
 - Failure factor: $\kappa = 0$;
 - Failure rate: see table below;

N_f	$\Phi = \frac{N_f}{N}$
13	1%
25	2%
51	4%
101	8%
202	16%

Table 2: Number of failures (N_f) and corresponding failure rate ($\Phi = \frac{N_f}{N}$).

²In order to model *isotropic* radiators, let us assume that the embedded elements patterns are equal to $F_\theta^{(n)}(u, v) = 1$ and $F_\varphi^{(n)}(u, v) = 0$, for $n = 1, \dots, N$.

- Measurement set-up
 - Type of sampling: uniform sampling in the (u, v) plane;
 - Number of points in the visible range: $K = 1257$;
 - Ratio between measurements and number of elements: $\nu = \frac{K}{N} \simeq 1.0$ ($\nu^{(opt)}$);
- *BCS* solver
 - Noise variance: $\eta = 5 \times 10^{-1}$ ($\eta^{(opt)}$);
 - Tolerance factor: $\iota = 10^{-8}$;
- Signal-to-Noise-Ratio: $SNR = \{10; 20; \dots; 100\}$.

$\Phi = \frac{N_f}{N} = 2\%$ ($N_f = 25$) - Best and Worst *BCS* Reconstructions

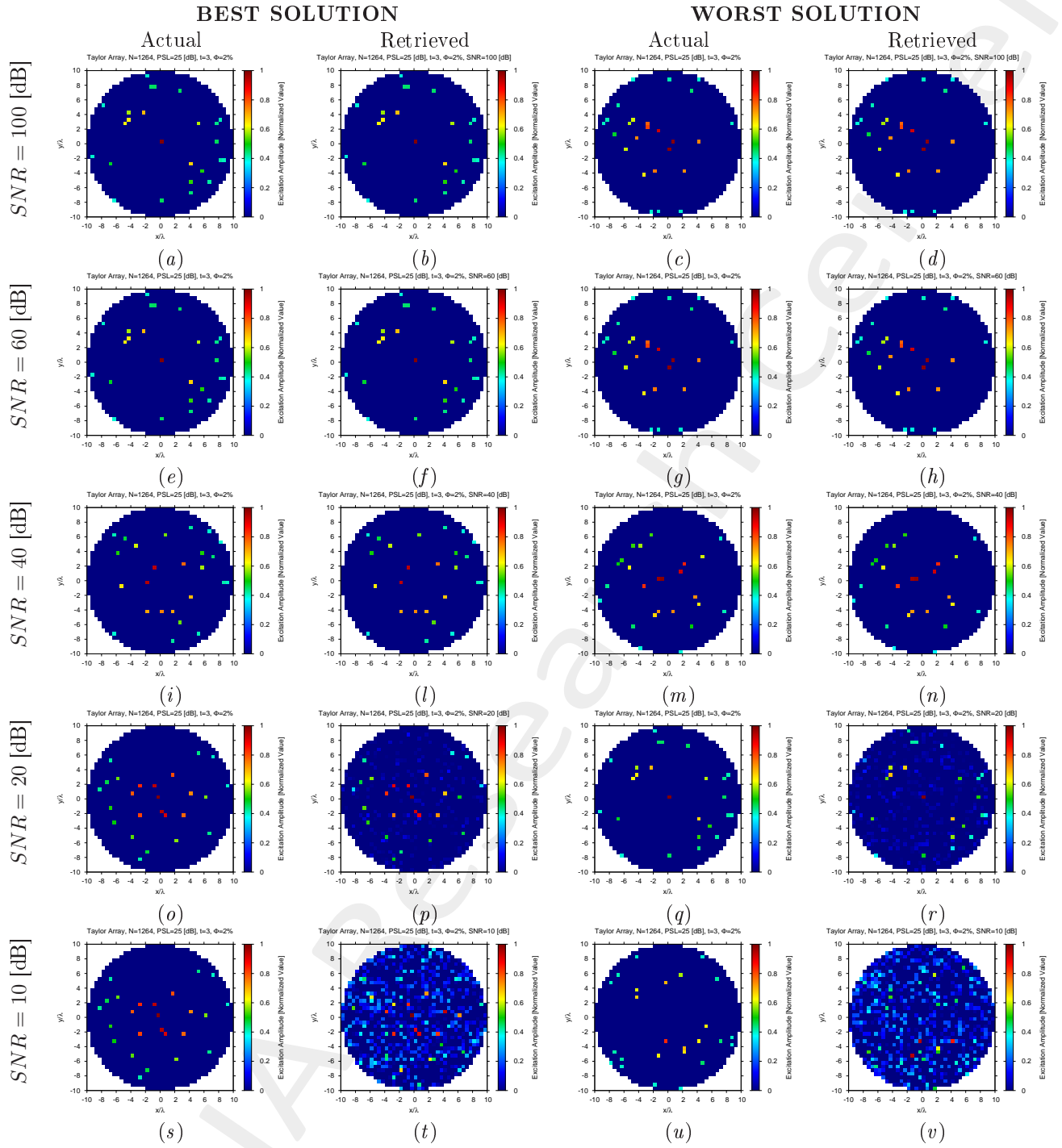


Figure 11: Taylor Array ($N = 1264$, $PSL = 25$ [dB], $t = 3$, $\Phi = 2\%$) - Best and worst reconstructions by *BCS* under several *SNR* values.

$\Phi = \frac{N_f}{N} = 4\%$ ($N_f = 51$) - Best and Worst *BCS* Reconstructions

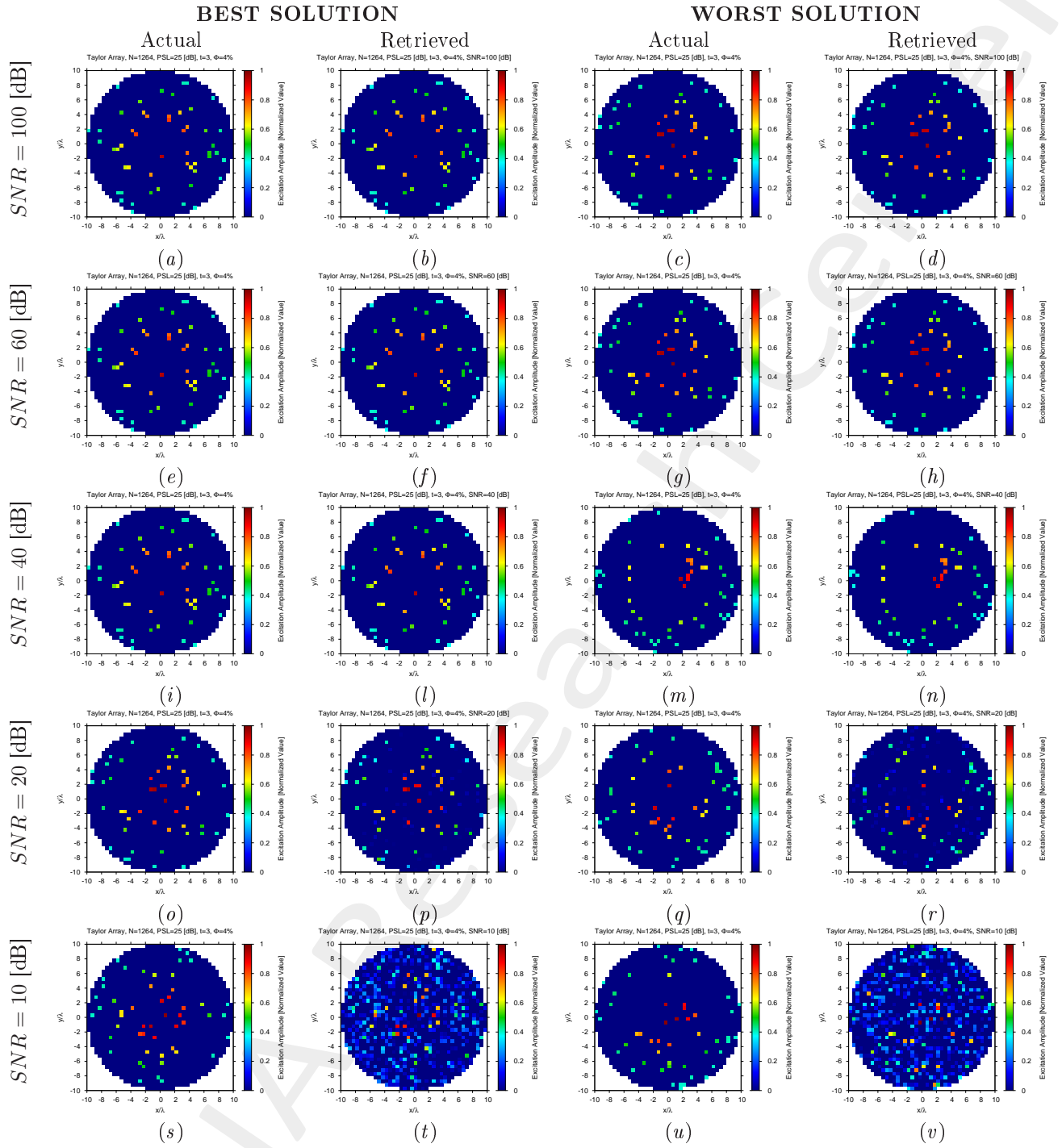


Figure 12: Taylor Array ($N = 1264$, $PSL = 25$ [dB], $t = 3$, $\Phi = 4\%$) - Best and worst reconstructions by *BCS* under several *SNR* values.

$\Phi = \frac{N_f}{N} = 8\%$ ($N_f = 101$) - Best and Worst *BCS* Reconstructions

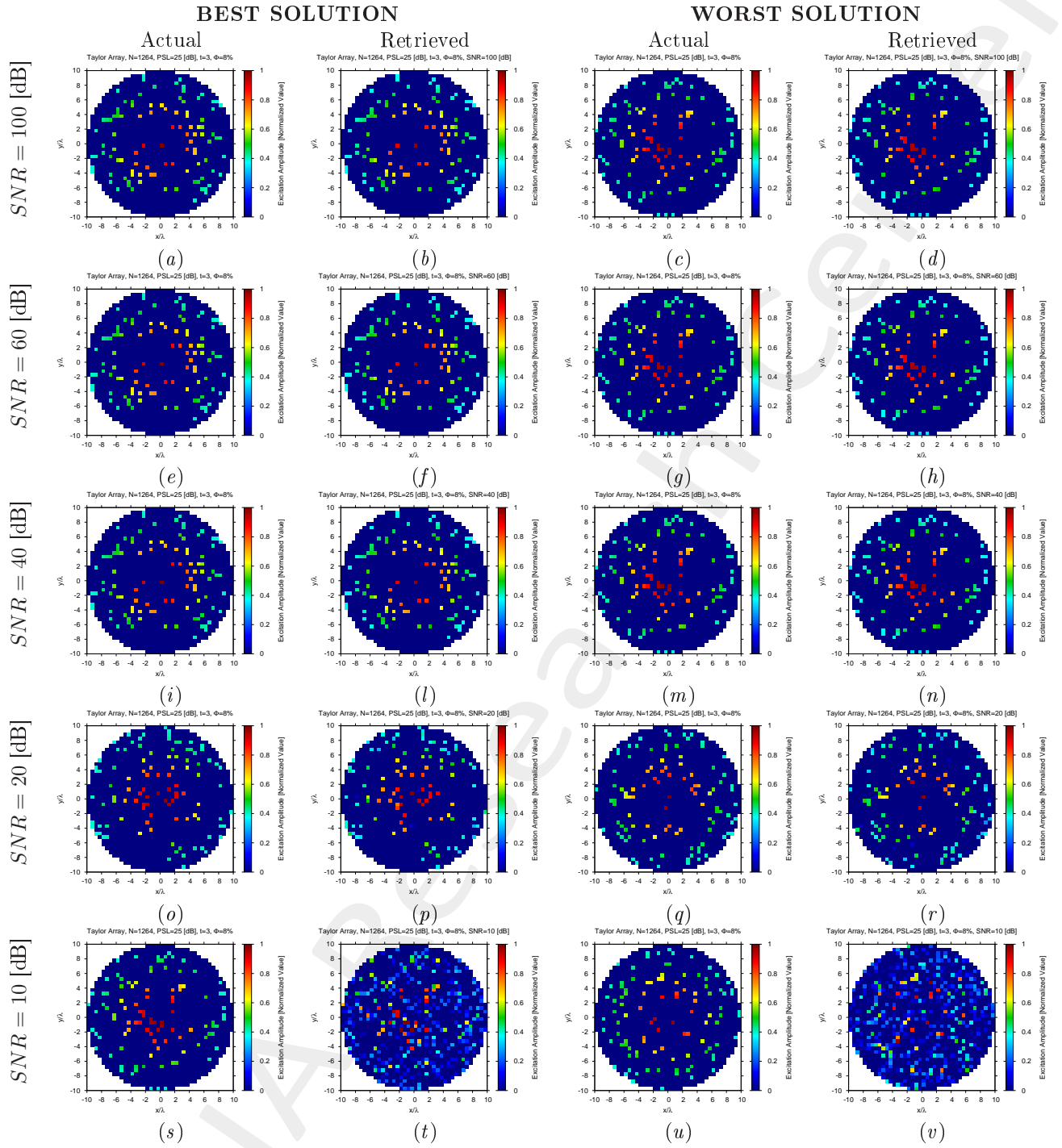


Figure 13: Taylor Array ($N = 1264$, $PSL = 25$ [dB], $t = 3$, $\Phi = 8\%$) - Best and worst reconstructions by *BCS* under several *SNR* values.

$\Phi = \frac{N_f}{N} = 16\%$ ($N_f = 202$) - Best and Worst *BCS* Reconstructions

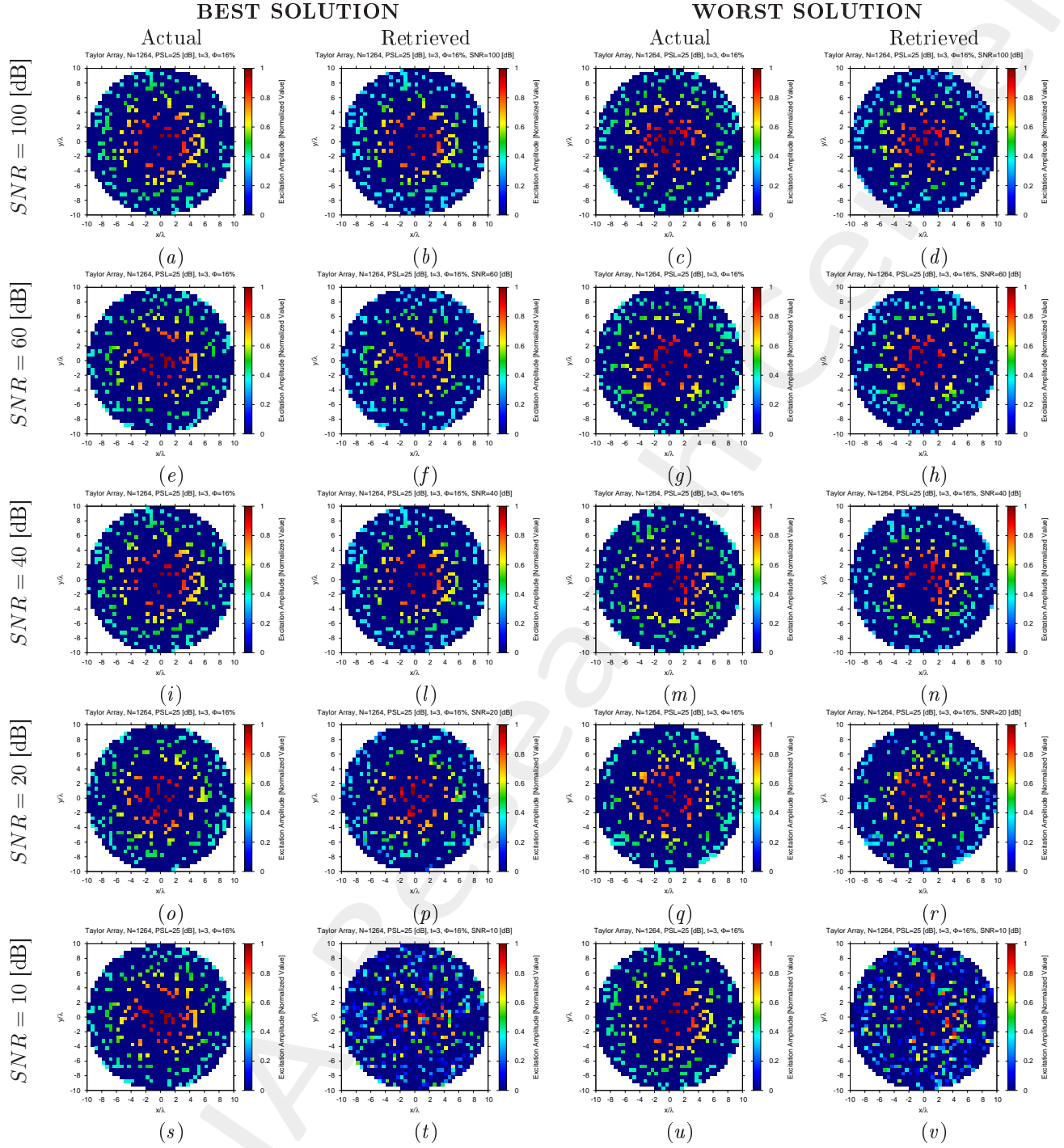


Figure 14: Taylor Array ($N = 1264$, $PSL = 25$ [dB], $t = 3$, $\Phi = 16\%$) - Best and worst reconstructions by *BCS* under several *SNR* values.

Diagnosis Error and Confidence Level

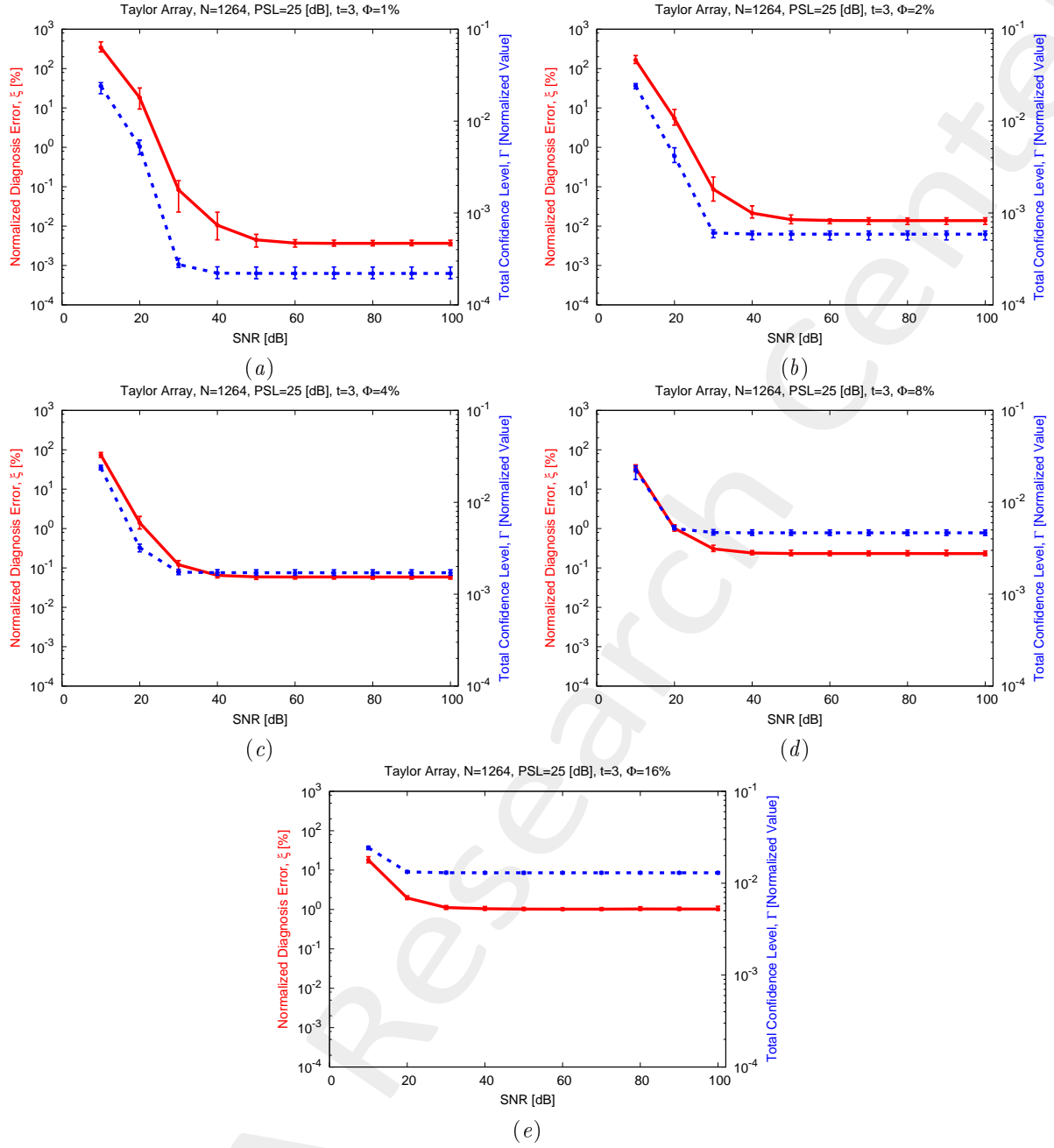


Figure 15: Taylor Array ($N = 1264$, $PSL = 25$ [dB], $t = 3$) - Behavior of the average, minimum and maximum diagnosis error (ξ) and total confidence level (Γ) versus the SNR , for (a) $\Phi = 1\%$, (b) $\Phi = 2\%$, (c) $\Phi = 4\%$, (d) $\Phi = 8\%$, and (e) $\Phi = 16\%$.

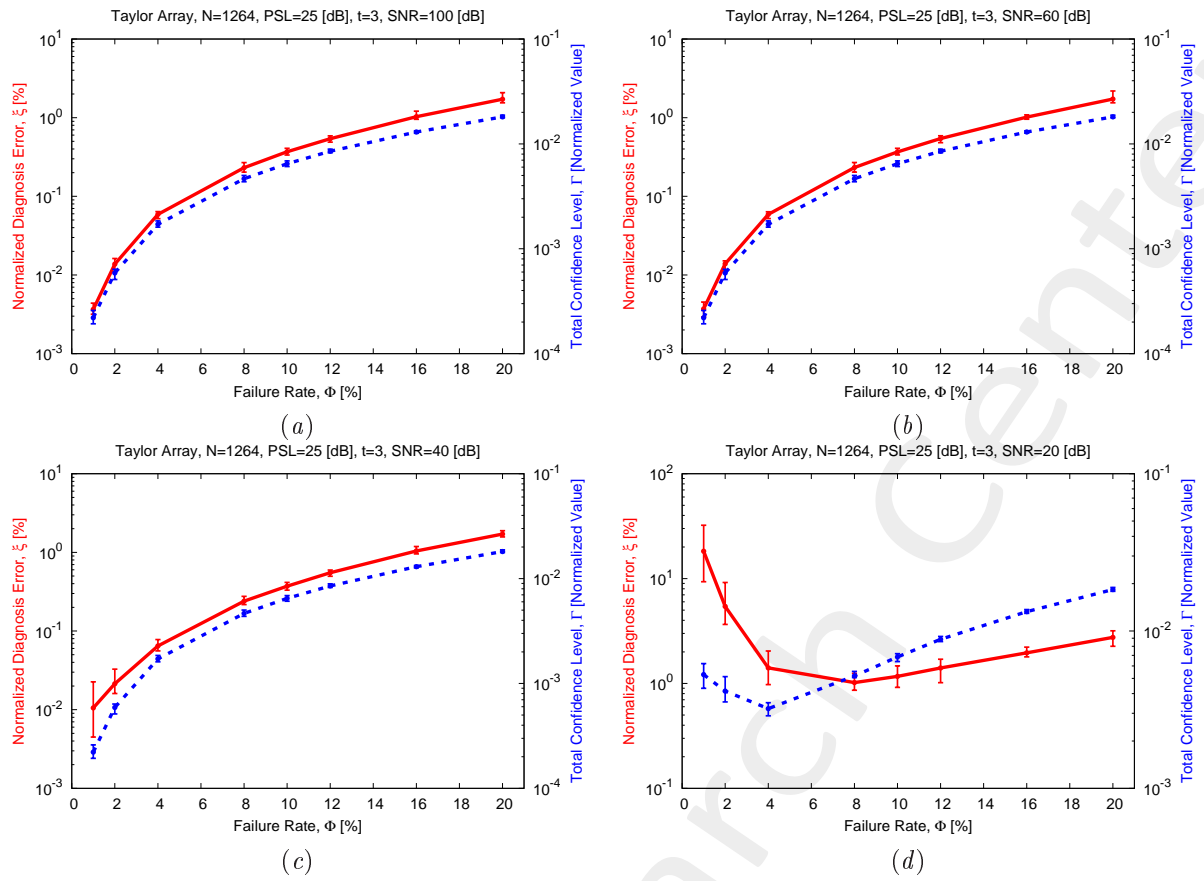


Figure 16: Taylor Array ($N = 1264$, $PSL = 25$ [dB], $t = 3$) - Behavior of the average, minimum and maximum diagnosis error (ξ) and total confidence level (Γ) versus the failure rate (Φ), for (a) $SNR = 100$ [dB], (b) $SNR = 60$ [dB], (c) $SNR = 40$ [dB], and (d) $SNR = 20$ [dB].

1.3 Taylor Array, $N = 1976$, Isotropic Sources

Parameters

- Gold Array
 - Total number of elements: $N = 1976$;
 - Type of elements: isotropic/ideal³;
 - Spacing along x and y : $d_x = d_y = 0.5 [\lambda]$;
 - Excitation tapering: Taylor;
 - * Radius: $R = 12.5 [\lambda]$;
 - * Transition index: $t = 3$;
 - * Peak sidelobe level: $PSL = 25 [\text{dB}]$;

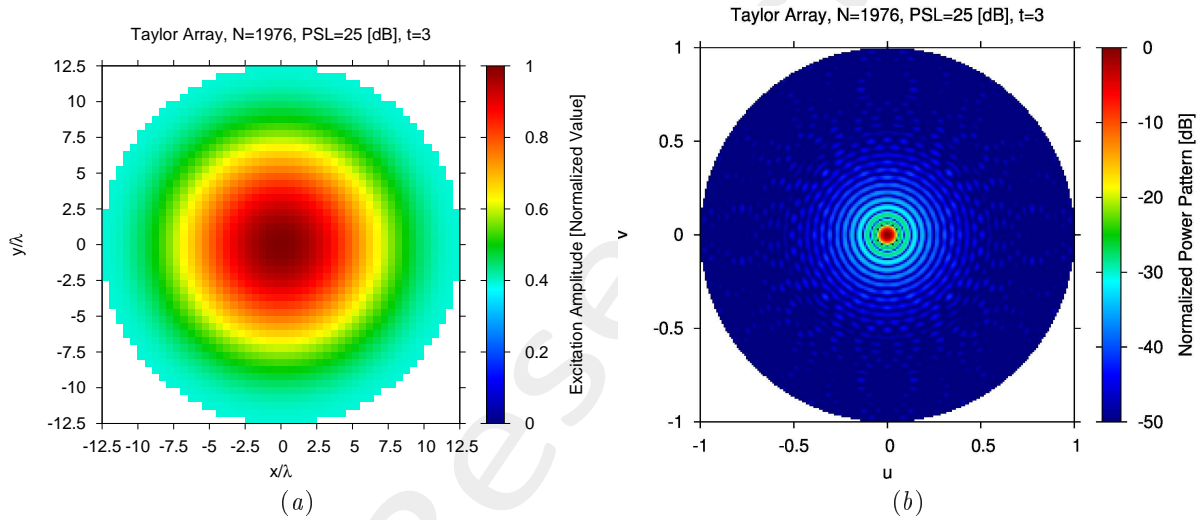


Figure 17: (a) Array excitations and (b) normalized power pattern of the expected array (gold antenna).

- Failed Array
 - Failure factor: $\kappa = 0$;
 - Failure rate: see table below;

N_f	$\Phi = \frac{N_f}{N}$
20	1%
40	2%
79	4%
158	8%
316	16%

Table 3: Number of failures (N_f) and corresponding failure rate ($\Phi = \frac{N_f}{N}$).

³In order to model *isotropic* radiators, let us assume that the embedded elements patterns are equal to $F_\theta^{(n)}(u, v) = 1$ and $F_\varphi^{(n)}(u, v) = 0$, for $n = 1, \dots, N$.

- Measurement set-up
 - Type of sampling: uniform sampling in the (u, v) plane;
 - Number of points in the visible range: $K = 1961$;
 - Ratio between measurements and number of elements: $\nu = \frac{K}{N} \simeq 1.0$ ($\nu^{(opt)}$);
- *BCS* solver
 - Noise variance: $\eta = 5 \times 10^{-1}$ ($\eta^{(opt)}$);
 - Tolerance factor: $\iota = 10^{-8}$;
- Signal-to-Noise-Ratio: $SNR = \{10; 20; \dots; 100\}$.

Results

$\Phi = \frac{N_f}{N} = 1\%$ ($N_f = 20$) - Best and Worst *BCS* Reconstructions

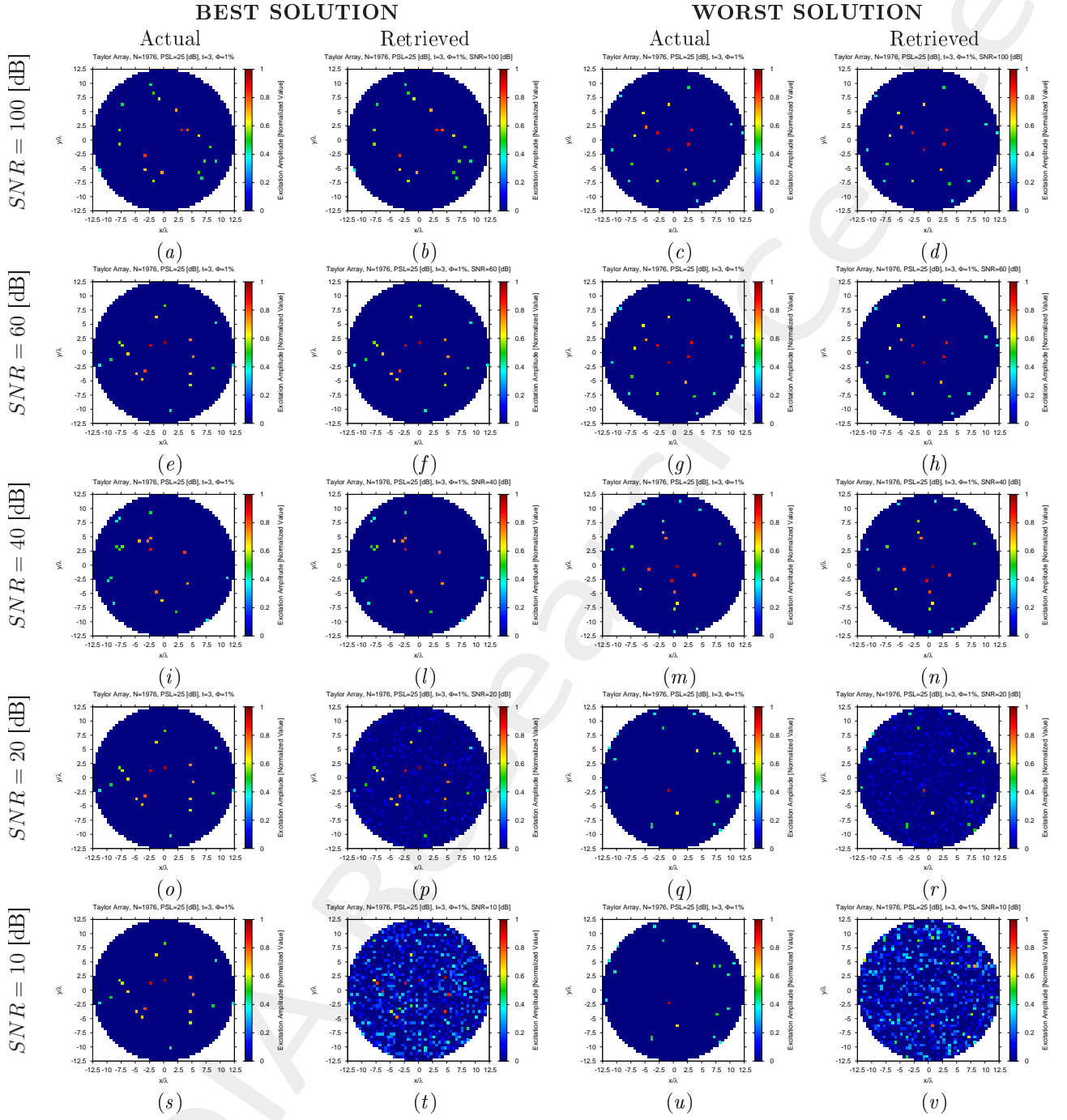


Figure 18: Taylor Array ($N = 1976$, $PSL = 25$ [dB], $t = 3$, $\Phi = 1\%$) - Best and worst reconstructions by *BCS* under several *SNR* values.

$\Phi = \frac{N_f}{N} = 2\%$ ($N_f = 40$) - Best and Worst *BCS* Reconstructions

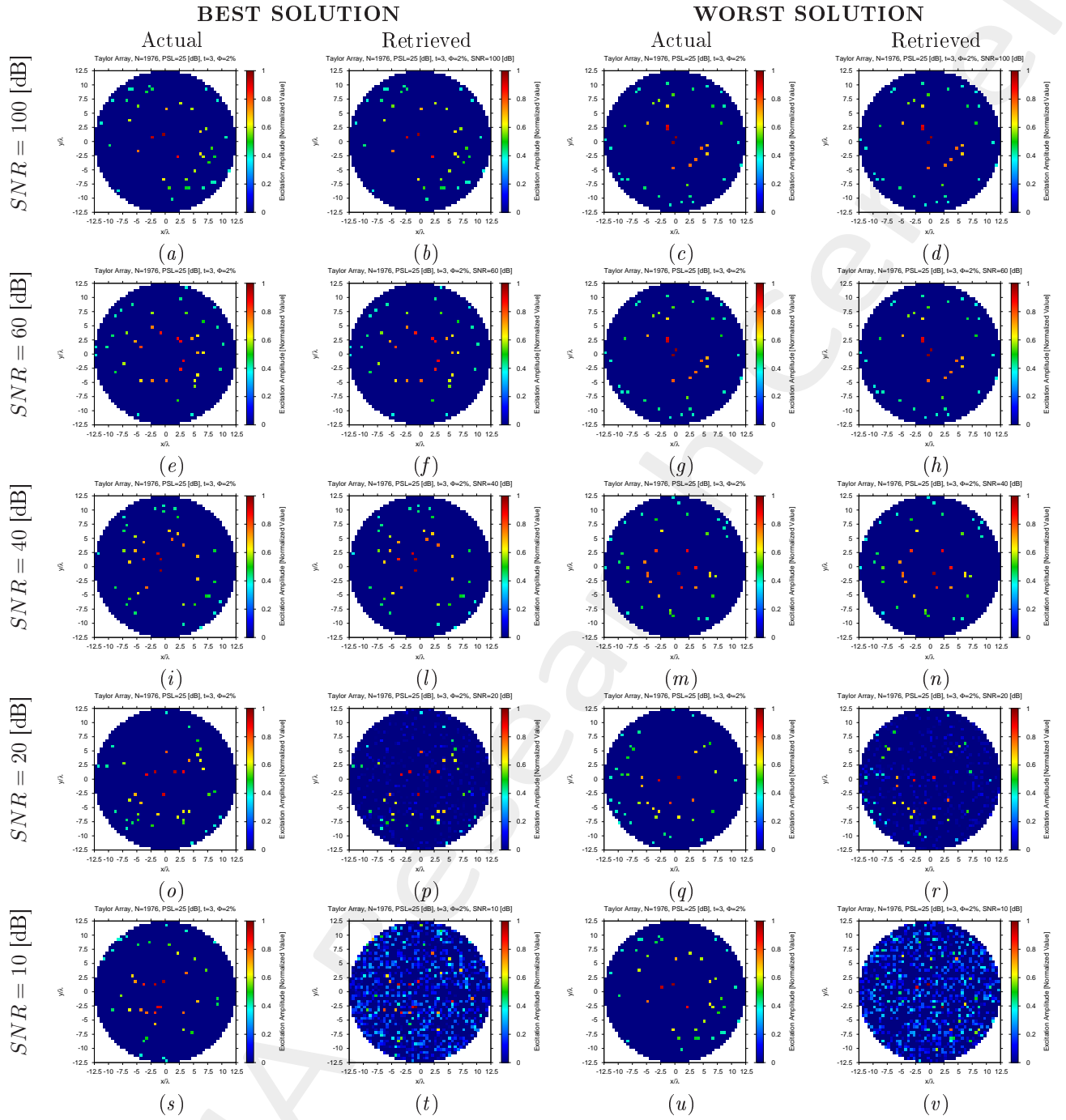


Figure 19: Taylor Array ($N = 1976$, $PSL = 25$ [dB], $t = 3$, $\Phi = 2\%$) - Best and worst reconstructions by *BCS* under several *SNR* values.

$\Phi = \frac{N_f}{N} = 4\%$ ($N_f = 79$) - Best and Worst *BCS* Reconstructions

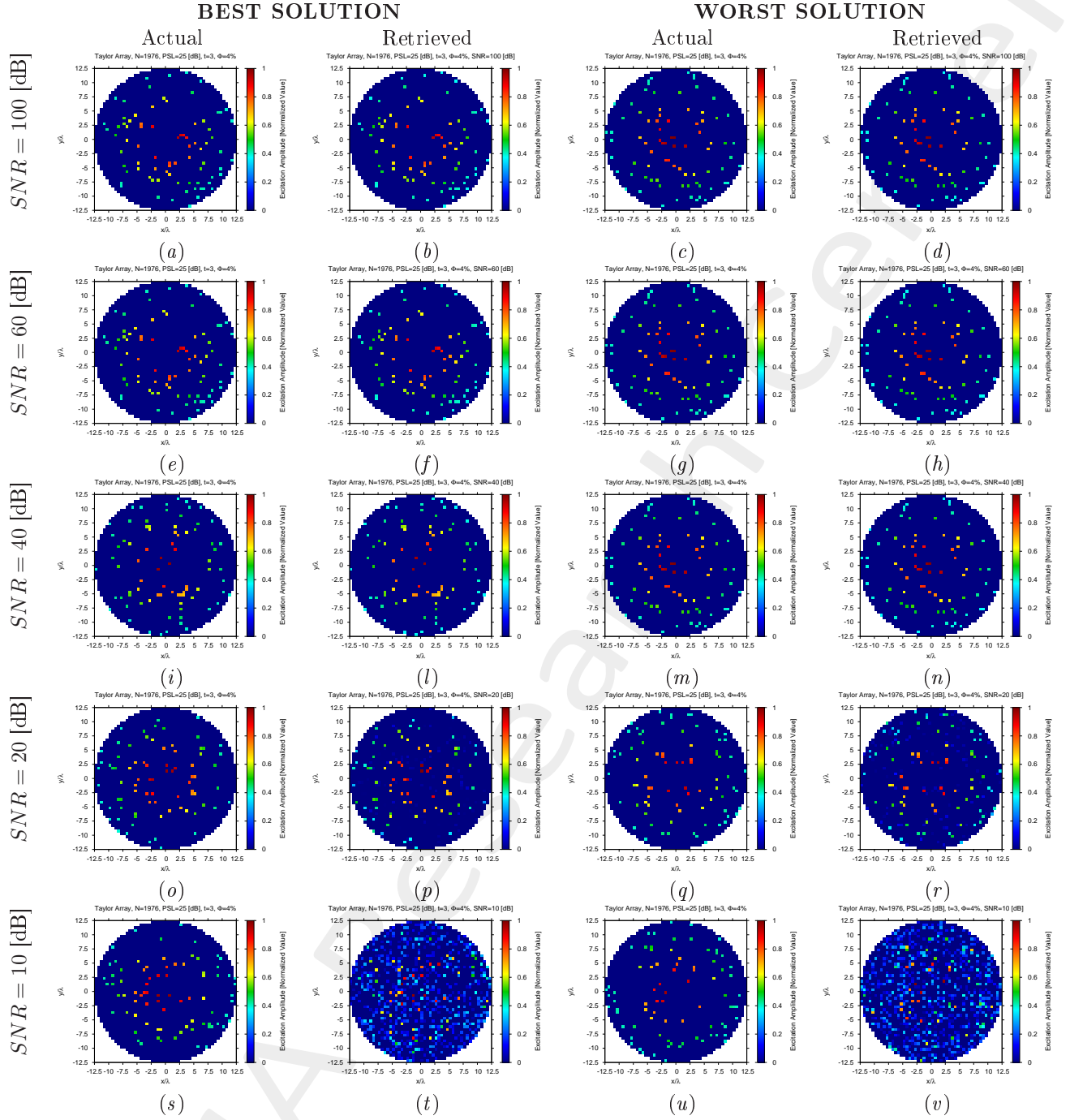


Figure 20: Taylor Array ($N = 1976$, $PSL = 25$ [dB], $t = 3$, $\Phi = 4\%$) - Best and worst reconstructions by *BCS* under several *SNR* values.

$\Phi = \frac{N_f}{N} = 8\%$ ($N_f = 158$) - Best and Worst BCS Reconstructions

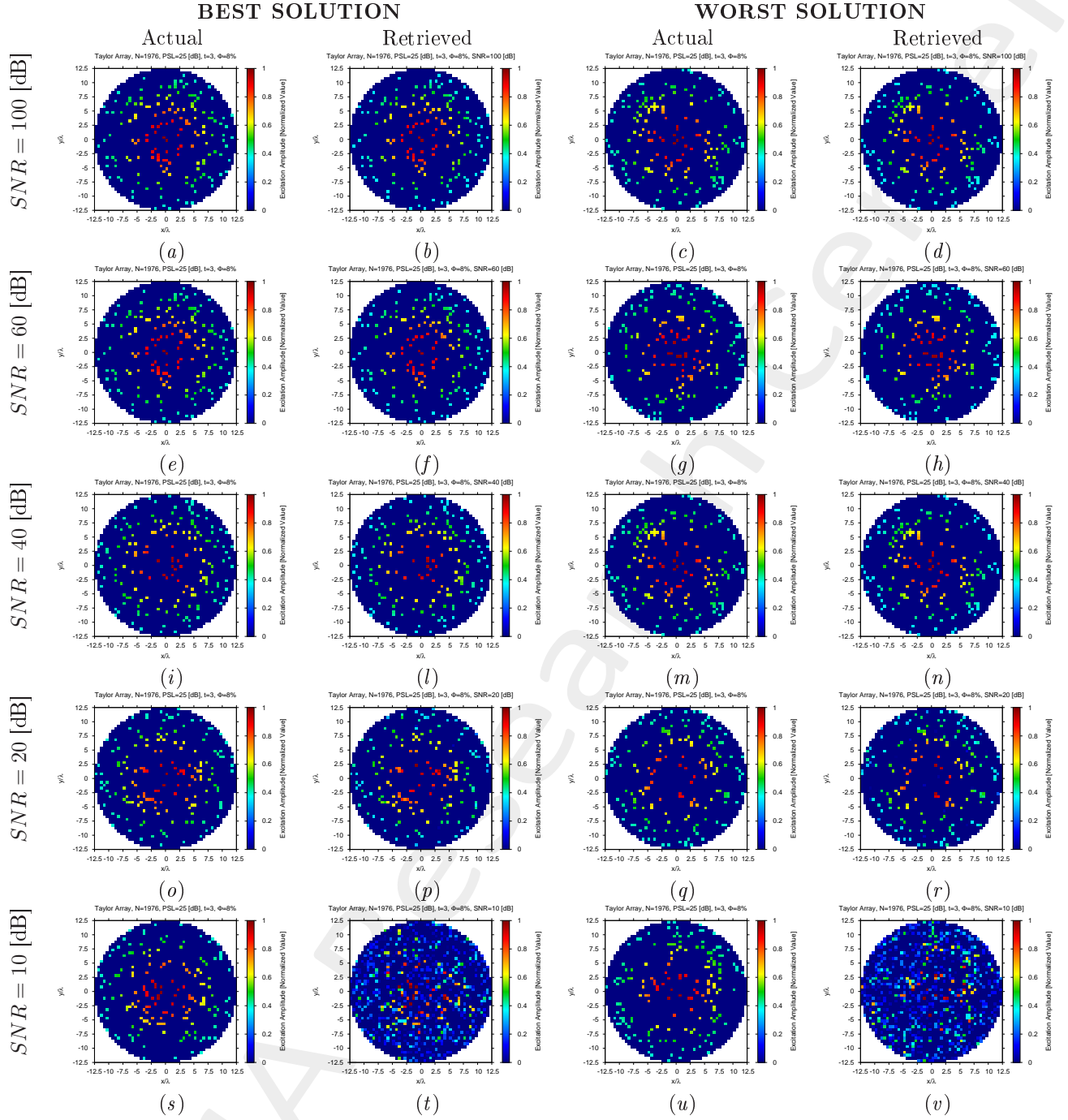


Figure 21: Taylor Array ($N = 1976$, $PSL = 25$ [dB], $t = 3$, $\Phi = 8\%$) - Best and worst reconstructions by BCS under several SNR values.

$\Phi = \frac{N_f}{N} = 16\%$ ($N_f = 316$) - Best and Worst *BCS* Reconstructions

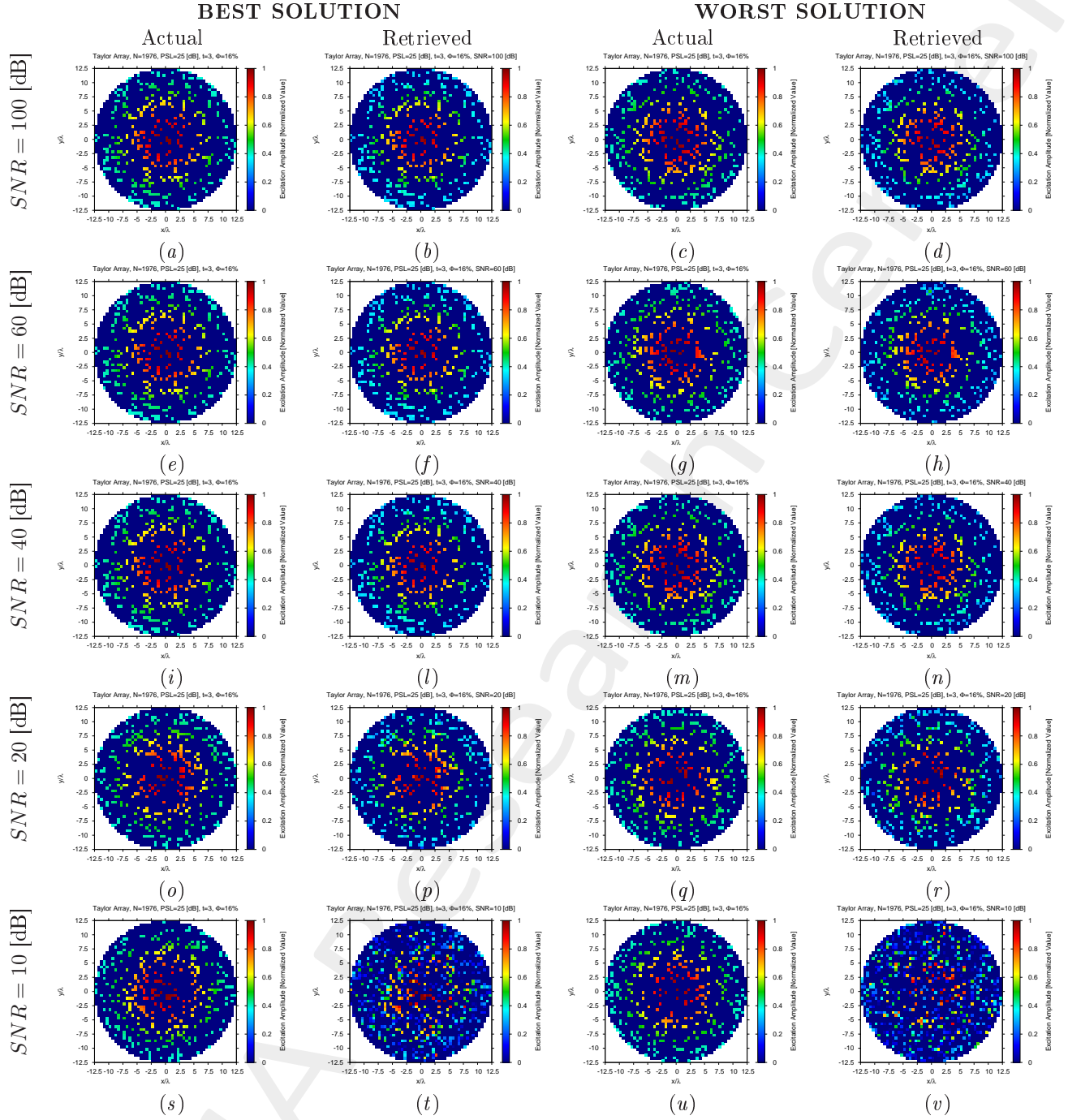


Figure 22: Taylor Array ($N = 1976$, $PSL = 25$ [dB], $t = 3$, $\Phi = 16\%$) - Best and worst reconstructions by *BCS* under several *SNR* values.

Diagnosis Error and Confidence Level

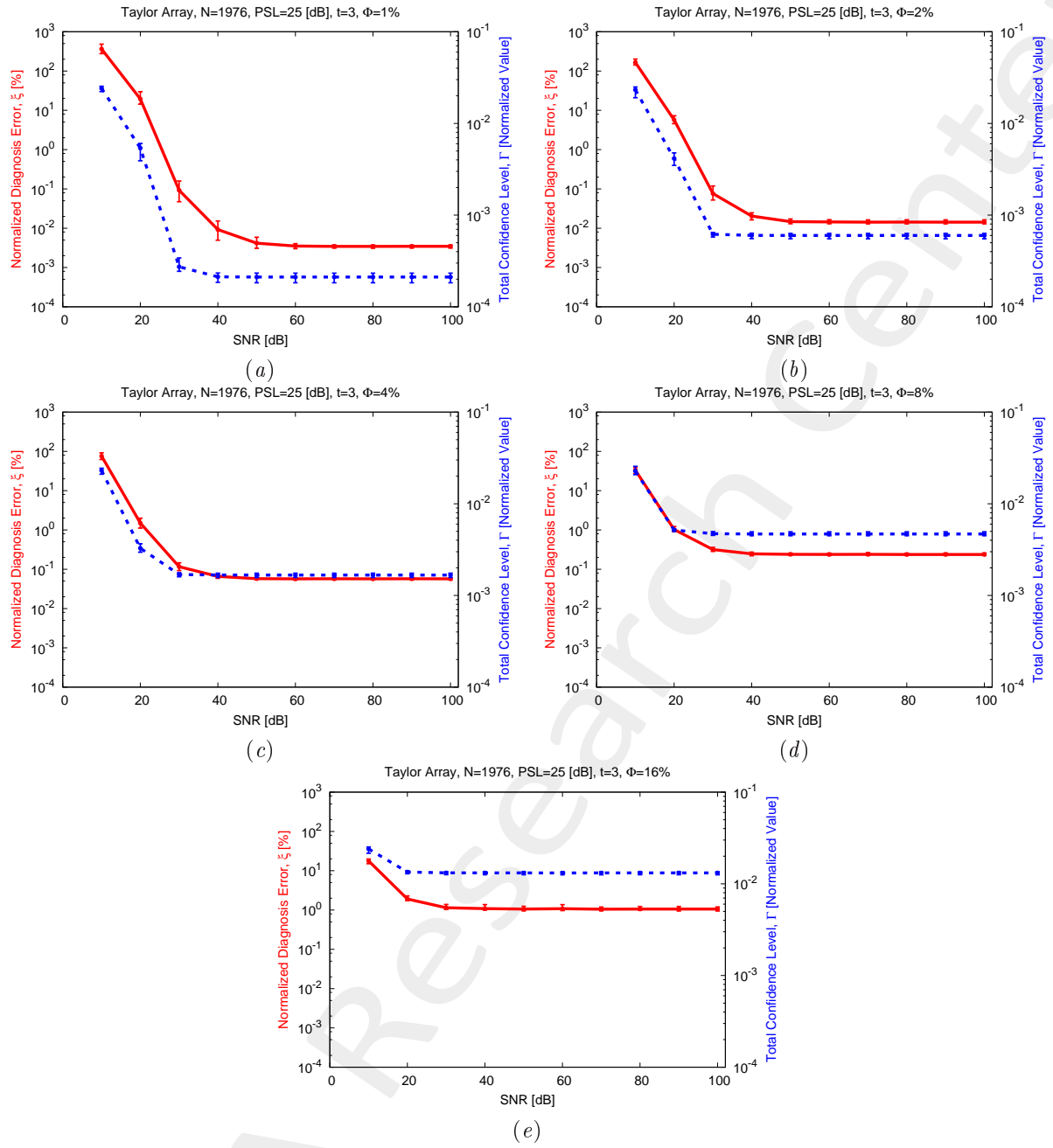


Figure 23: Taylor Array ($N = 1976$, $PSL = 25$ [dB], $t = 3$) - Behavior of the average, minimum and maximum diagnosis error (ξ) and total confidence level (Γ) versus the SNR , for (a) $\Phi = 1\%$, (b) $\Phi = 2\%$, (c) $\Phi = 4\%$, (d) $\Phi = 8\%$, and (e) $\Phi = 16\%$.

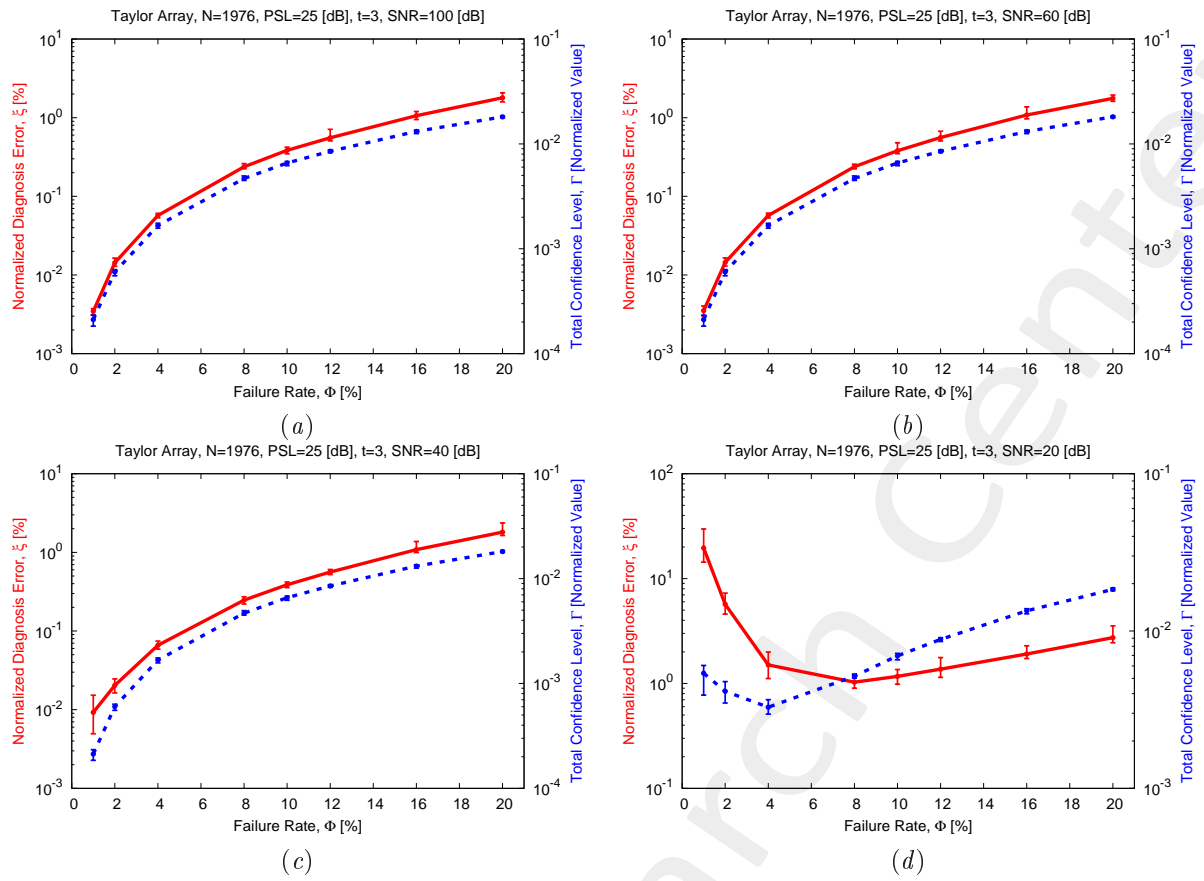


Figure 24: Taylor Array ($N = 1976$, $PSL = 25$ [dB], $t = 3$) - Behavior of the average, minimum and maximum diagnosis error (ξ) and total confidence level (Γ) versus the failure rate (Φ), for (a) $SNR = 100$ [dB], (b) $SNR = 60$ [dB], (c) $SNR = 40$ [dB], and (d) $SNR = 20$ [dB].

1.4 Taylor Array, Analysis vs. Array Size (N)

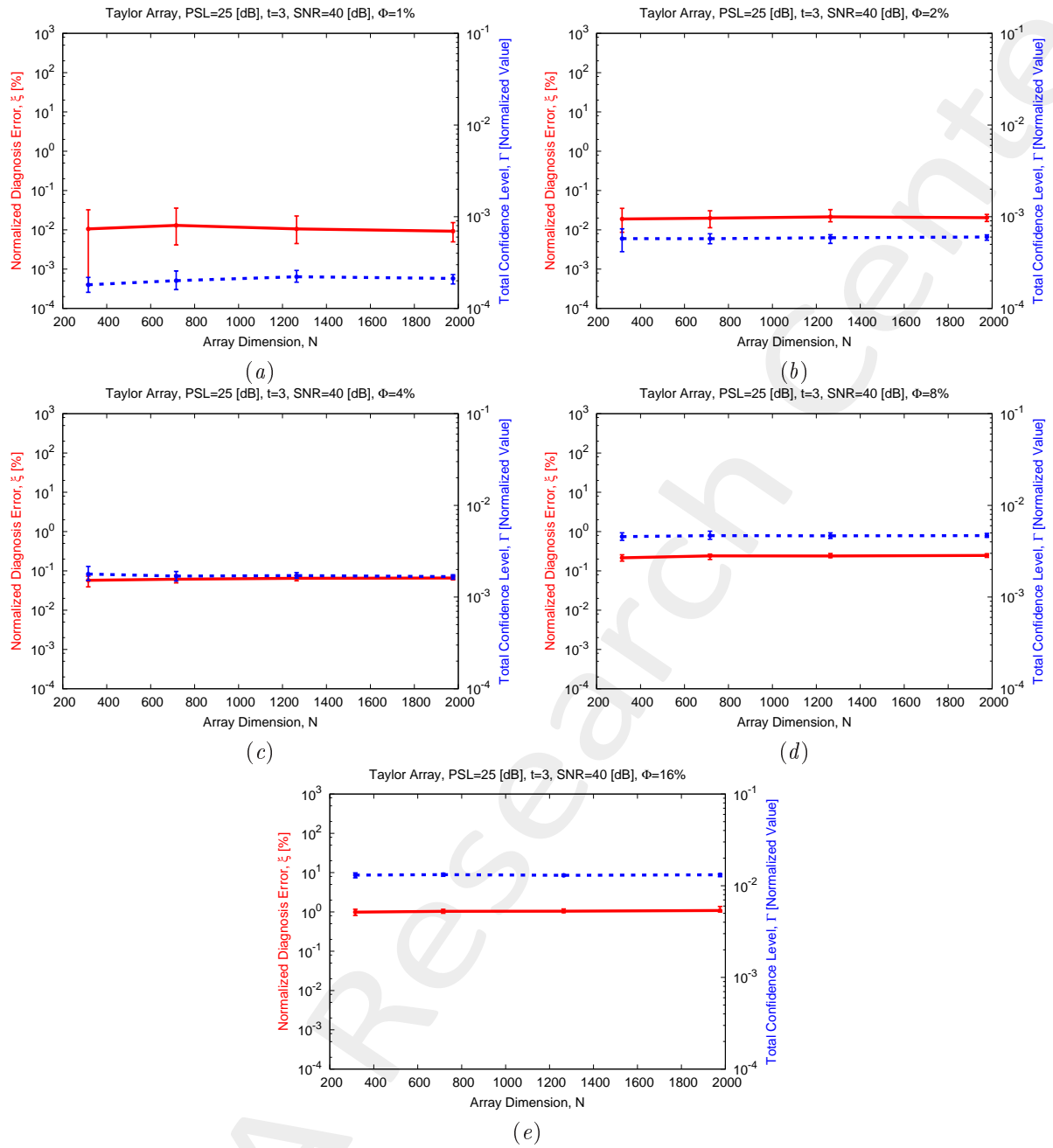


Figure 25: Taylor Array ($PSL = 25$ [dB], $t = 3$), $SNR = 40$ [dB] - Behavior of the average, minimum and maximum diagnosis error (ξ) and total confidence level (Γ) versus the array dimension (N), for (a) $\Phi = 1\%$, (b) $\Phi = 2\%$, (c) $\Phi = 4\%$, (d) $\Phi = 8\%$, and (e) $\Phi = 16\%$.

More information on the topics of this document can be found in the following list of references.

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