

# NDT-NDE Crack Characterization Through a Learning-by-Examples Approach

M. Salucci, N. Anselmi, G. Oliveri, and A. Massa

## Abstract

This document deals with the characterization of a single narrow crack in a planar conductive structure starting from eddy current testing (*ECT*) measurements. More precisely, the inversion problem at hand is formulated within the so-called learning-by-examples (*LBE*) paradigm, by considering the problem of estimating the dimensions of the defect as a regression one. Accordingly, a set of known input-output pairs is generated during an *off-line* phase and is given as input to a Support Vector Regressor (*SVR*) prediction model in order to train it on the relationship between defect and corresponding *ECT* data. Some numerical results are shown in order to verify the effectiveness, as well as the limits, of the proposed *LBE* technique when dealing with the presence of noise on testing data during the *on-line* inversion phase.

# 1 Crack Dimensions Estimation Inside a Plate Structure

## 1.1 Description

Let be given an homogeneous plate of thickness  $T$  and conductivity  $\sigma$  affected by a narrow crack and inspected by a single coil working in absolute mode at frequency  $f$  with lift-off  $\delta$  (Fig. 1). The dimensions of the crack are completely described by the vector  $\mathbf{p}$  of  $I = 3$  parameters

$$\mathbf{p} = \{d_0, l_0, w_0\} \quad (1)$$

which correspond to its depth, length and width, respectively. Moreover, we assume that the location of the crack (identified by the triplet of coordinates  $(x_0, y_0, z_0)$ ) is fixed and known (Fig. 1).

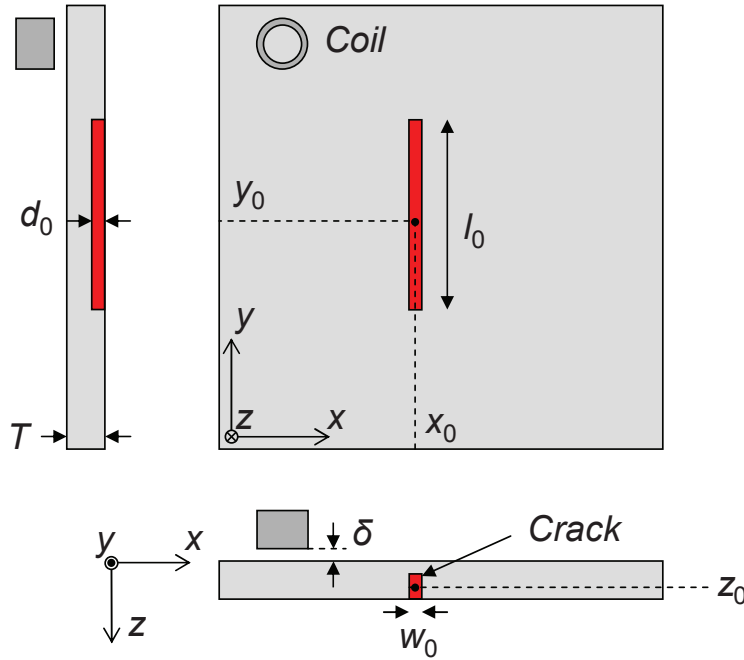


Figure 1: Geometry of the problem.

A metamodel is used as forward solver to compute in a fast but accurate way the measured  $ECT$  signal associated to a particular dimension of the defect. More in details, for a given vector  $\mathbf{p}$  of crack descriptors, the metamodel computes the complex  $ECT$  signal over a set of  $K$  measurement points uniformly distributed on the  $(x, y)$  plane

$$\Psi = \Phi \{\mathbf{p}\} = \{\Psi_k; k = 1, \dots, K\} \quad (2)$$

where

- $\Psi_k = \Re \{\Psi_k\} + j\Im \{\Psi_k\}$  is the complex-valued  $ECT$  signal collected by the  $k$ -th measurement point (i.e., the impedance variation on the coil);

- $\Phi \{.\}$  is the forward operator, linking the defect barycentre ( $\mathbf{p}$ ) to the collected *ECT* signal ( $\Psi$ ).

The goal of the inverse problem is to retrieve an estimation of the (unknown) dimensions of the flaw  $\tilde{\mathbf{p}} = \{\tilde{d}_0, \tilde{l}_0, \tilde{w}_0\}$  (i.e., the output space) by exploiting the information embedded inside  $\Psi$  (i.e., the input space). Such a problem can be formulated as follows

$$\tilde{\mathbf{p}} = \Phi^{-1} \{ \Psi \} \quad (3)$$

where  $\Phi^{-1} \{.\}$  denotes the (unknown) inverse operator, that has to be estimated.

## 1.2 Parameters of the forward solver (fixed)

- **Forward solver**

- total number of measurement points along  $x$  (i.e., across the crack):  $H_x = 41$ ;
- measurement step along  $x$ :  $\Delta_x = 0.5$  [mm];
- total extension of the measurement region along  $x$ :  $L_x = 20.0$  [mm];
- total number of measurement points along  $y$  (i.e., along the crack):  $H_y = 57$ ;
- measurement step along  $y$ :  $\Delta_y = 0.5$  [mm];
- total extension of the measurement region along  $y$ :  $L_y = 28.0$  [mm];
- total number of measurement point computed by the forward solver:  $H = H_x \times H_y = 2337$ ;

<b>Plate</b>	
Thickness $T$	1.55 [mm]
Conductivity $\sigma$	1.02 [MS/m]
<b>Coil</b>	
Inner radius $r_1$	1.0 [mm]
Outer radius $r_2$	1.75 [mm]
Length $l_c$	2.0 [mm]
Number of turns $n_t$	328
Lift-off $\delta$	0.303 [mm]
Frequency $f$	100.0 [KHz]
<b>Crack</b>	
x-Coordinate $x_0$	15.0 [mm]
y-Coordinate $y_0$	15.0 [mm]
z-Coordinate $z_0$	1.24 [mm]

Table 1: Fixed parameters.

<b>Parameter</b>	<b>Min [mm]</b>	<b>Max [mm]</b>
Crack Depth $d_0$	0.31	1.24
Crack Length $l_0$	5.0	20.0
Crack Width $w_0$	0.05	0.4

Table 2: Validity ranges of the forward meta-model.

### 1.3 Standard *LBE* Approach (*GRID – SVR*): Performances

#### 1.3.1 Parameters

- Measurement set-up for the inversion

- considered measurement step:  $\Delta_x = \Delta_y = 0.5$  [mm];
- number of considered measurement points  $K = K_x \times K_y = 5 \times 31 = 155$ ;
- measured quantity for each  $k$ -th point:  $\{\Re(\Psi_k), \Im(\Psi_k)\}$ ;
- total number of measured features:  $F = 2 \times K = 310$ ;

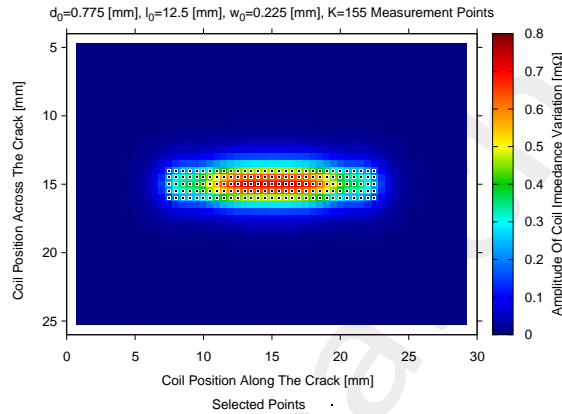


Figure 2: Location of the measurement points selected for the inversion ( $K = 155$ ).

- Standard *LBE* Approach

- Training set generation
  - \* sampling: uniform grid sampling in  $(d_0, l_0, w_0)$ ;
  - \* number of quantization levels:  $Q_{x_0} = Q_{y_0} = Q_{z_0} = \{5; 6; \dots; 10\}$ ;
  - \* number of training samples:  $N = Q_{x_0} \times Q_{y_0} \times Q_{z_0} = \{125; 216; \dots; 1000\}$ ;
  - \* *SNR* on training data: Noiseless;
- Test set generation
  - \* Sampling: Latin Hypercube Sampling (*LHS*);
  - \* Number of test samples:  $M = 1000$ ;
  - \* *SNR* on test data: Noiseless +  $SNR = \{40; 30; 20; 10\}$  [dB].

### 1.3.2 Calibration of the SVR parameters via cross-validation

The best  $(C, \gamma)$  pair of parameters is selected for training the three SVR regressors.

#### Parameters

- number of subsets:  $V = 5$ ;
- variation range for parameter  $C$ :  $C \in \{10^0; 10^1; \dots; 10^6\}$ ;
- variation range for parameter  $\gamma$ :  $\gamma \in \{10^{-5}; 10^{-5}; \dots; 10^0\}$ ;
- dimension of the training set:  $N = 1000$ ;

#### Results

Parameter	Best $C$ ( $C^*$ )	Best $\gamma$ ( $\gamma^*$ )	CV MSE ( $\eta$ )
Crack Depth $d_0$	$10^3$	$10^{-3}$	$2.12 \times 10^{-3}$
Crack Length $l_0$	$10^4$	$10^{-2}$	$4.53 \times 10^{-3}$
Crack Width $w_0$	$10^6$	$10^{-4}$	$2.34 \times 10^{-3}$

Table 3: Optimal  $(C, \gamma)$  pairs and CV MSE found by applying a 5-fold cross-validation for the estimation of the crack dimensions.

### 1.3.3 True vs. Predicted ( $SNR = 20$ [dB])

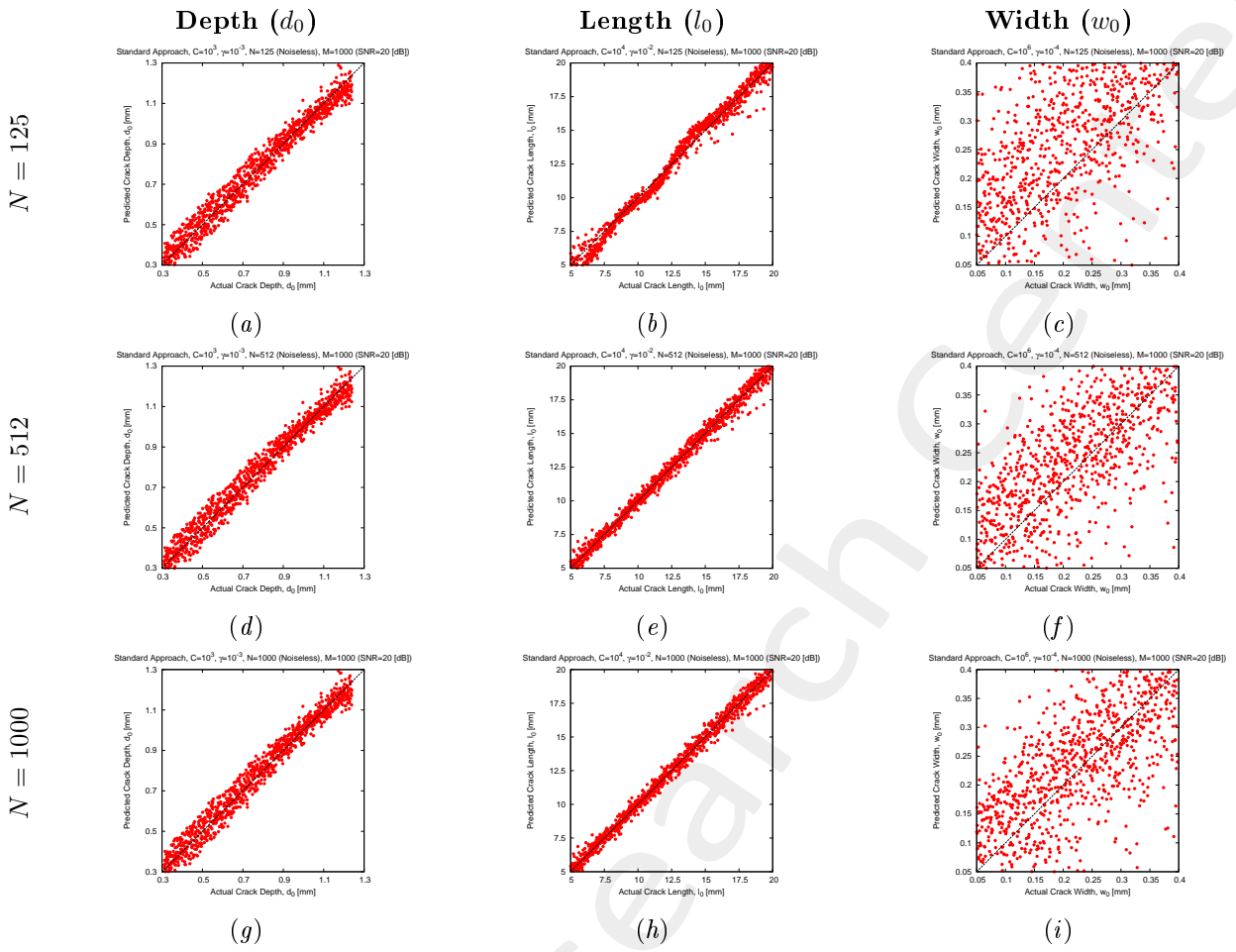


Figure 3: **Standard Approach** - True vs. predicted crack dimensions for different dimensions of the training set ( $N$ ).  $SNR = 20$  [dB] on test *ECT* data.

### 1.3.4 Prediction Errors

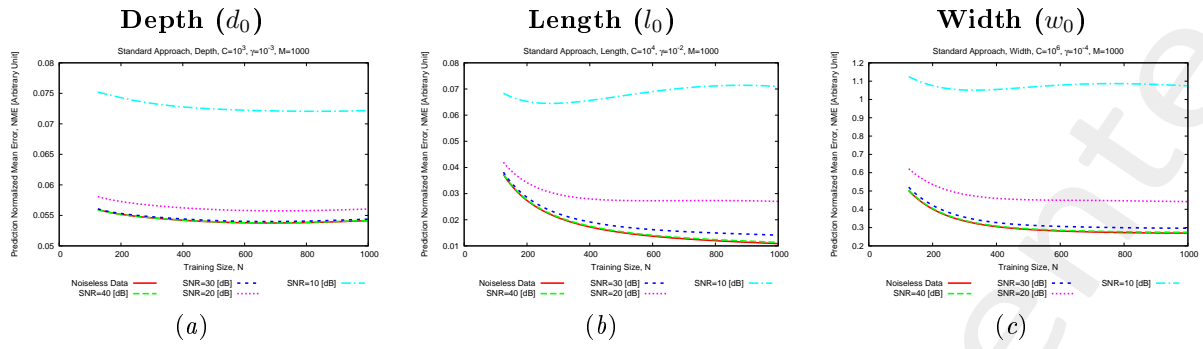


Figure 4: **Standard Approach** - Normalized Mean Error ( $NME$ ) vs. training size ( $N$ )

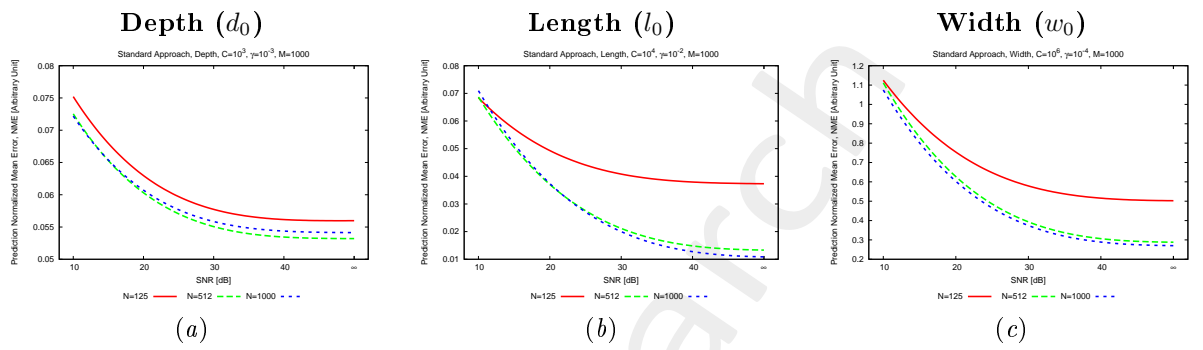


Figure 5: **Standard Approach** - Normalized Mean Error ( $NME$ ) vs.  $SNR$  on the test  $ECT$  measurements.

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More information on the topics of this document can be found in the following list of references.

## References

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